## Programming (Econometrics) Lecture 4: Program correctness

#### Tommi Tervonen

#### Econometric Institute, Erasmus School of Economics



## Counting sum of the elements of an integer array

```
public static int countSum(int[] array) {
  for (int i=1;i<array.length;i++) {
    array[i] = array[i] + array[i-1];
  }
  return array[array.length -1];
}</pre>
```

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}</pre>
```

- Returns the correct value, but also modifies the parameter array as a side effect.
- What would you expect from:

public static int countSum(int[] array)



- Unexpected side effects make code difficult to understand
- There are also *desired* side effects, e.g. sorting the contents of an array
- In Java we have
  - Accessor methods: returning a value but not modifying contents of the object (public int getAge())
  - Mutator methods: modifying the contents of the object but not returning a value (public void setAge(int age))



### Functions and procedures

- In imperative programming we classify methods into
  - Functions, that return a value but do not alter the parameters in any way
  - Procedures, that alter some of the parameters but do not return a value
- void setElement(Matrix m, int rlnd, int clnd, double newElement)

**double** getElement(Matrix m, **int** rlnd, **int** clnd)

 Note: if the language does not support exceptions (e.g. C), procedures often do return a value for signifying error conditions

- For side effects to be possible, parameters have to be passed by reference: only a reference (memory address) of the variable is passed to the called method
- Other main technique for parameter passing is to pass by value: a local copy of the variable is created within the called method
- Example: pass by reference vs pass by value



- Matlab passes everything by value
- Matrices are passed by reference until they are modified the first time, at which point a local copy is created (!)
- The OO-extension allows to pass references by value by using the handle class



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- Pros:
  - No undesired side effects
- Cons:
  - No desired side effects
  - Many algorithms can be expressed more clearly with procedures
  - Recursive algorithms become slow without procedures

```
function A = sort(A)
    leftList = A(1:middle);
    rightList = A((middle+1):length(A));
    leftList = sort(leftList);
    rightList = sort(rightList);
    A = merge(leftList, rightList);
end
```

- Methods define a *contract* between the supplier (you) and the consumer (you or someone else)
- Contract **partially** defined through the signature:

function arr = sortArrayFromIndex(array, index)



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Contends

Contract:

- I The index has to be in the range [1, length(array)] (responsibility of the consumer)
- 2 If consumer calls the method adhering to (1), then after the method call the following holds: array[index] < array[index+1] < ... < array[length(array)] (responsibility of the supplier)

```
% Sorts the array in ascending order starting
% from index
%
% PRECOND: 0 < index <= length(array)
% POSTCOND: arr(index) < ...
% ... < arr(length(array))
function arr = sortArrayFromIndex(array, index)
```

- Responsibilities of the consumer are method *pre-conditions* ("Requires")
- Responsibilities of the supplier are method *post-conditions* ("Ensures")
- (PRECOND, METHOD)  $\Rightarrow$  POSTCOND

- As a supplier, if the pre-condition is violated, you are not responsible for what happens
- In practice you should crash the program execution, as the mistake is in the logic

function array = sortFromIndex(array, index)
 assert(index > 0 && index <= length(array));
 ... % do the actual sorting
end</pre>

- If you cannot handle a possible parameter value, you should declare the accepted range as a pre-conditions
- Post-conditions are often stated in a more informal manner in the method documentations
- Document post-conditions when doing more complex programs, and when you have problems finding bugs



### $(PRECOND, METHOD) \Rightarrow POSTCOND$

How do we know that METHOD ever terminates execution? How do we know that METHOD does what it's supposed to?

## Stop or not?

```
nr = input("How many integers you want?");
for(i=1:nr)
    printf("%d th integer\n", i);
    pause(10*i);
end
```

```
green = true;
while(green)
green = false;
pause(10);
green = true;
end
```



# Alan Turing (1912-54)



- Designed the computer that cracked german Enigma in WW2
- Invented LU decomposition
- Invented the Turing test
- Proved the following



Given programs indexed using x, input i, assume that there is a computable function h(x, i):

$$h(x,i) = \begin{cases} 1 & \text{if } x \text{ halts with input } i \\ 0 & \text{otherwise} \end{cases}$$

As we have von Neumann computers (programs = data), we can also call h(x, x)

Now, take an arbitrary total computable function f, and construct a partial computable function

$$g(x) = egin{cases} 0 & ext{if } f(x,x) = 0 \ ext{undefined} & ext{otherwise} \end{cases}$$

g is computable by a program e that loops forever on the undefined case ( $\implies h$  is defined on e)

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#### $\implies$ no such computable function as h

 $\implies$  the halting problem is undecidable

We cannot algorithmically determine whether a program stops execution